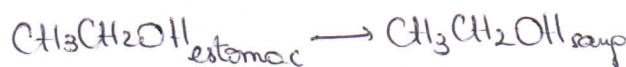


Exercice 1

1)  $v_1 = - \frac{d[\text{CH}_3\text{CH}_2\text{OH}]_{\text{estomac}}}{dt}$



$t=0$	$C_1 V_1$	$0$
$t$	$(C_1 - x) V_1$	$x V_1$

$v_1 = \frac{dx}{dt}$

2) on trace  $[\text{CH}_3\text{CH}_2\text{OH}]_{\text{estomac}}(t)$ , on fait une régression linéaire :

$r^2 \approx 1 \rightarrow$  ordre 1 valide

pende =  $-k_1 \rightarrow k_1 = 0,17 \text{ min}^{-1}$

3) a)  $[\text{CH}_3\text{CH}_2\text{OH}]_{\text{sang}} = \frac{x V_1}{V_2}$        $x V_1 = m (\text{CH}_3\text{CH}_2\text{OH}_{\text{sang}}) \text{ à } t$   
 b)  $\left\{ \right.$

c)  $C_2 = \frac{x V_1}{V_2}$       à  $t = 18 \text{ min} : [\text{CH}_3\text{CH}_2\text{OH}]_{\text{estomac}} = 0,2 \text{ mol/L } (= C_1 - x)$   
 à  $t = 0$        $[\text{CH}_3\text{CH}_2\text{OH}]_{\text{estomac}} = 4 \text{ mol/L } (= C_1)$

$C_2 = \frac{(4 - 0,2) \times 250 \times 10^{-3}}{40} = 0,024 \text{ mol/L}$

d)  $v = \frac{d[\text{CH}_3\text{CH}_2\text{OH}]_{\text{sang}}}{dt} = \frac{dx}{dt} \times \frac{V_1}{V_2} \rightarrow v = \frac{V_1}{V_2} v_1$

4)  $v_2 = - \frac{d[\text{CH}_3\text{CH}_2\text{OH}]_{\text{sang}}}{dt}$

5) on trace  $[\text{CH}_3\text{CH}_2\text{OH}]_{\text{sang}}(t)$ , on fait une régression linéaire :

$r^2 \approx 1 \rightarrow$  ordre 0 valide

pende =  $-k_2 \rightarrow k_2 = 7,1 \times 10^{-5} \text{ mol.L}^{-1}.\text{min}^{-1}$

6)  $C_{\text{max}} = \frac{0,5}{46} = 0,011 \text{ mol/L}$

ordre 1  $= v_1 = \frac{dx}{dt} = k_1 [\text{CH}_3\text{CH}_2\text{OH}]_{\text{estomac}} = k_1 C_1 \exp(-k_1 t)$

ordre 0  $\Rightarrow v_2 = k_2$

7)  $\frac{dC_0}{dt} = \underset{\substack{\uparrow \\ \text{apparition}}}{v} - \underset{\substack{\uparrow \\ \text{disparition}}}{v_2} = \frac{V_1}{V_2} \frac{dx}{dt} - v_2$

$$\Rightarrow \frac{dC_2}{dt} = \frac{V_1}{V_2} k_1 C_1 \exp(-k_1 t) - k_2 C_2$$

$$8) C_2 = -\frac{V_1}{V_2} C_1 \exp(-k_1 t) - k_2 t + C_0$$

$\downarrow$   
 or à  $t=0$   $C_2=0$

$$\text{donc } C_0 = \frac{V_1}{V_2} C_1$$

$$\rightarrow C_2 = \frac{V_1}{V_2} C_1 (1 - \exp(-k_1 t)) - k_2 t$$

$$9) \left. \begin{array}{l} V_1 = 66 \text{ cL} = 0,66 \text{ L} \\ C_1 = \frac{0,9}{0,66} \end{array} \right\} C_1 V_1 = 0,9 \text{ mol} \quad V_2 = 4 \text{ L}$$

$$C_2 \text{ est maximale } (\Leftrightarrow \left(\frac{dC_2}{dt}\right) = 0 \Leftrightarrow \frac{V_1}{V_2} k_1 C_1 \exp(-k_1 t_{\max}) = k_2$$

$$t_{\max} = \ln\left(\frac{k_2 V_2}{k_1 C_1 V_1}\right) \times \frac{1}{-k_1} = 23,5 \text{ min}$$

$$10) C_2(t_{\max}) = 0,02 \text{ mol/L} > C_{\max} \rightarrow \text{il ne peut pas conduire}$$

$$11) \text{ si } t \rightarrow \infty \quad C_2(t) \simeq -k_2 t + \frac{V_1}{V_2} C_1 \quad (\Leftrightarrow \text{droite de pente } (-k_2))$$

$$C_2 = C_{\max} \Leftrightarrow -k_2 t_{\text{ok}} + \frac{V_1}{V_2} C_1 = 0,011 \Rightarrow t_{\text{ok}} = 162 \text{ min soit } 2 \text{ h } 42 \text{ min}$$

## Exercice 2

$$1) m l \ddot{\theta} + \alpha l \dot{\theta} + m g \theta = 0 \quad (\Leftrightarrow \text{oscillateur harmonique amorti})$$

$$2) \ddot{\theta} + \frac{\alpha}{m} \dot{\theta} + \frac{g}{l} \theta = 0 \quad \omega_0^2 = \frac{g}{l} \Rightarrow \omega_0 = \sqrt{\frac{g}{l}}$$

$$\frac{\omega_0}{Q} = \frac{\alpha}{m} \rightarrow Q = \frac{\omega_0 m}{\alpha} = \sqrt{\frac{g}{l}} \times \frac{m}{\alpha}$$

$$3) a) \text{ le régime est pseudo-périodique } (\Leftrightarrow Q > \frac{1}{2})$$

$$b) X^2 + \frac{\omega_0}{Q} X + \omega_0^2 = 0 \quad \Delta = \omega_0^2 \left(\frac{1}{Q^2} - 4\right) = 4 \omega_0^2 \left(\frac{1}{4Q^2} - 1\right)$$

$$X_{\pm} = \frac{-\frac{\omega_0}{Q} \pm i \sqrt{4 \omega_0^2 \left(1 - \frac{1}{4Q^2}\right)}}{2} \quad \bullet \text{ pseudo-pulsation } \Omega = \omega_0 \sqrt{1 - \frac{1}{4Q^2}}$$

$$\bullet \text{ pseudo-période } T = \frac{2\pi}{\Omega} = \frac{2\pi}{\omega_0} \left(1 - \frac{1}{4Q^2}\right)^{-1/2}$$

on mesure  $T = 2,20 - 1,10 = 1,10 \text{ s}$

$$c) \theta(t) = \exp\left(-\frac{\omega_0 t}{2Q}\right) \left( A \cos(\Omega t) + B \sin(\Omega t) \right)$$

$$\theta(0) = \theta_0 \rightarrow A = \theta_0$$

$$\dot{\theta}(0) = 0 \rightarrow -\frac{\omega_0}{2Q} \times A + B \Omega = 0 \quad B = \frac{\omega_0 \theta_0}{2Q \Omega}$$

$$\rightarrow \theta(t) = \theta_0 \exp\left(-\frac{\omega_0 t}{2Q}\right) \left( \cos(\Omega t) + \frac{\omega_0}{2Q \Omega} \sin(\Omega t) \right)$$

$$d) \frac{\theta(t)}{\theta(t+T)} = \frac{\exp\left(-\frac{\omega_0 t}{2Q}\right) \theta_0 \left( \cos(\Omega t) + \frac{\omega_0}{2Q \Omega} \sin(\Omega t) \right)}{\exp\left(-\frac{\omega_0 (t+T)}{2Q}\right) \theta_0 \left( \cos(\Omega (t+T)) + \frac{\omega_0}{2Q \Omega} \sin(\Omega (t+T)) \right)} = \exp\left(\frac{\omega_0 T}{2Q}\right)$$

$$\left( \begin{array}{l} \cos(\Omega t) = \cos(\Omega (t+T)) \\ \sin(\Omega t) = \sin(\Omega (t+T)) \end{array} \right)$$

$$\hookrightarrow \delta = \frac{\omega_0 T}{2Q} = \ln\left(\frac{8,95}{8,02}\right) = 0,110$$

$$e) \frac{\omega_0 T}{2Q} = \delta \quad (\Rightarrow) \quad \frac{\omega_0}{Q} = \frac{2 \times 0,11}{1,10} = 0,20 \text{ s}^{-1}$$

$$\text{or } \alpha = \frac{\omega_0 m}{Q} = 9,4 \times 10^{-2} \text{ kg} \cdot \text{s}^{-1}$$

$$\Omega^2 = \omega_0^2 - \frac{\omega_0^2}{4Q^2} \quad \Leftrightarrow \quad \omega_0^2 = \Omega^2 + \frac{\omega_0^2}{4Q^2} = \left(\frac{2\pi}{T}\right)^2 + \frac{1}{4} \left(\frac{\omega_0}{Q}\right)^2$$

$$\omega_0 = \sqrt{\left(\frac{2\pi}{1,1}\right)^2 + \frac{1}{4} \times 0,2^2} = 5,71 \text{ rad} \cdot \text{s}^{-1}$$

$$Q = \frac{\omega_0 T}{2\delta} = \frac{5,71 \times 1,10}{2 \times 0,110} = 28,6$$